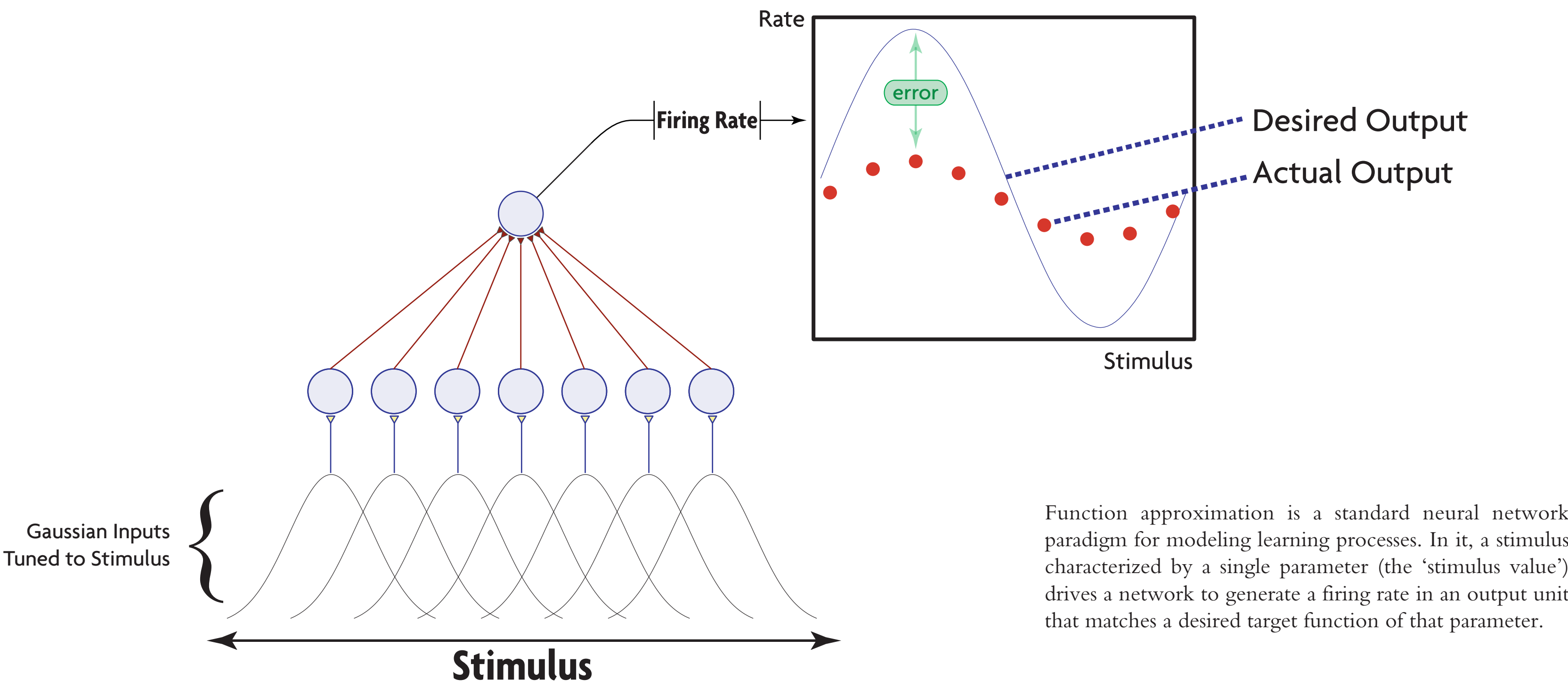


# Neuronal Supervision of Hebbian Synaptic Plasticity

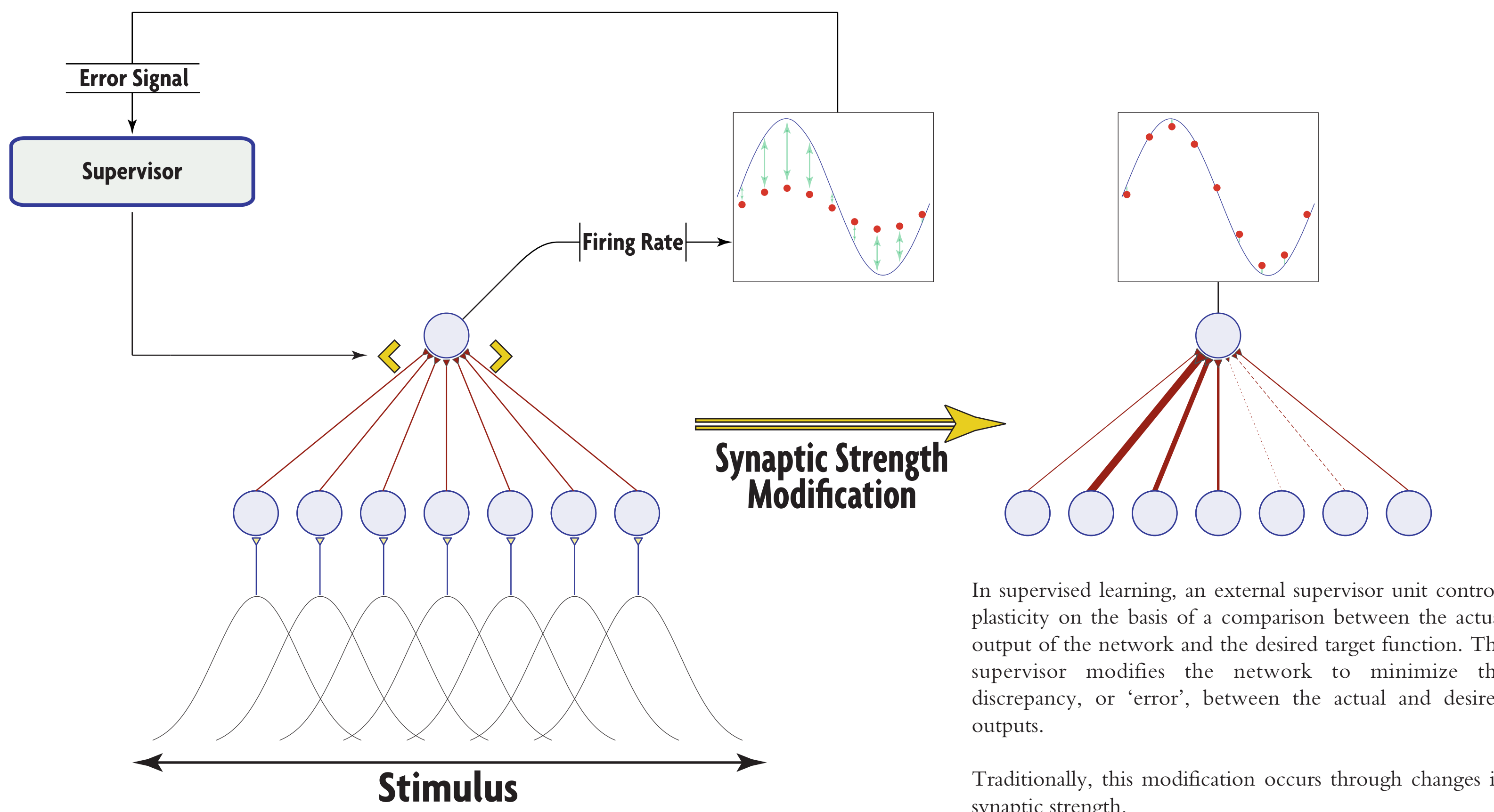
Christian D. Swinehart & L.F. Abbott

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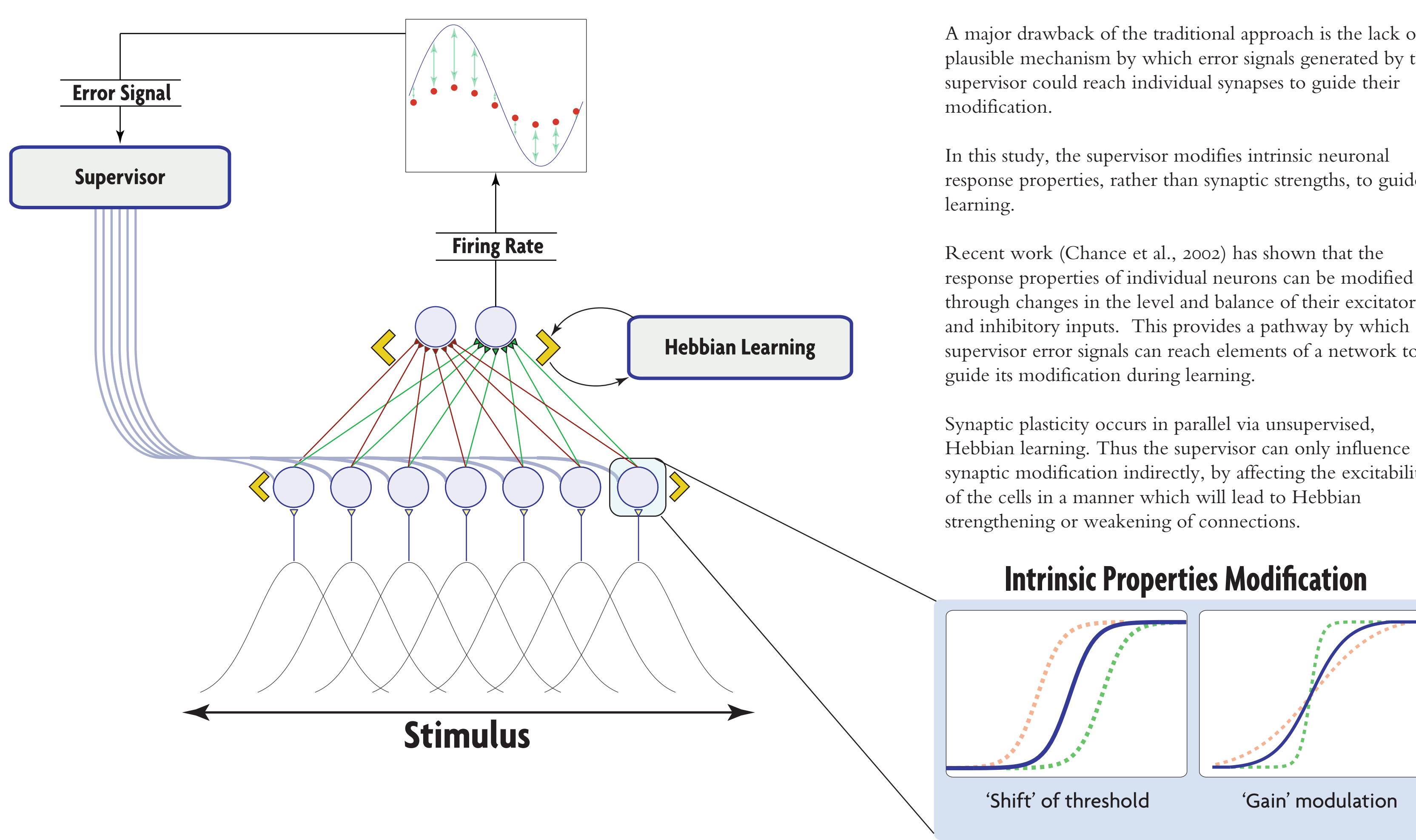
## Function Approximation Learning



### Traditional Supervised Learning

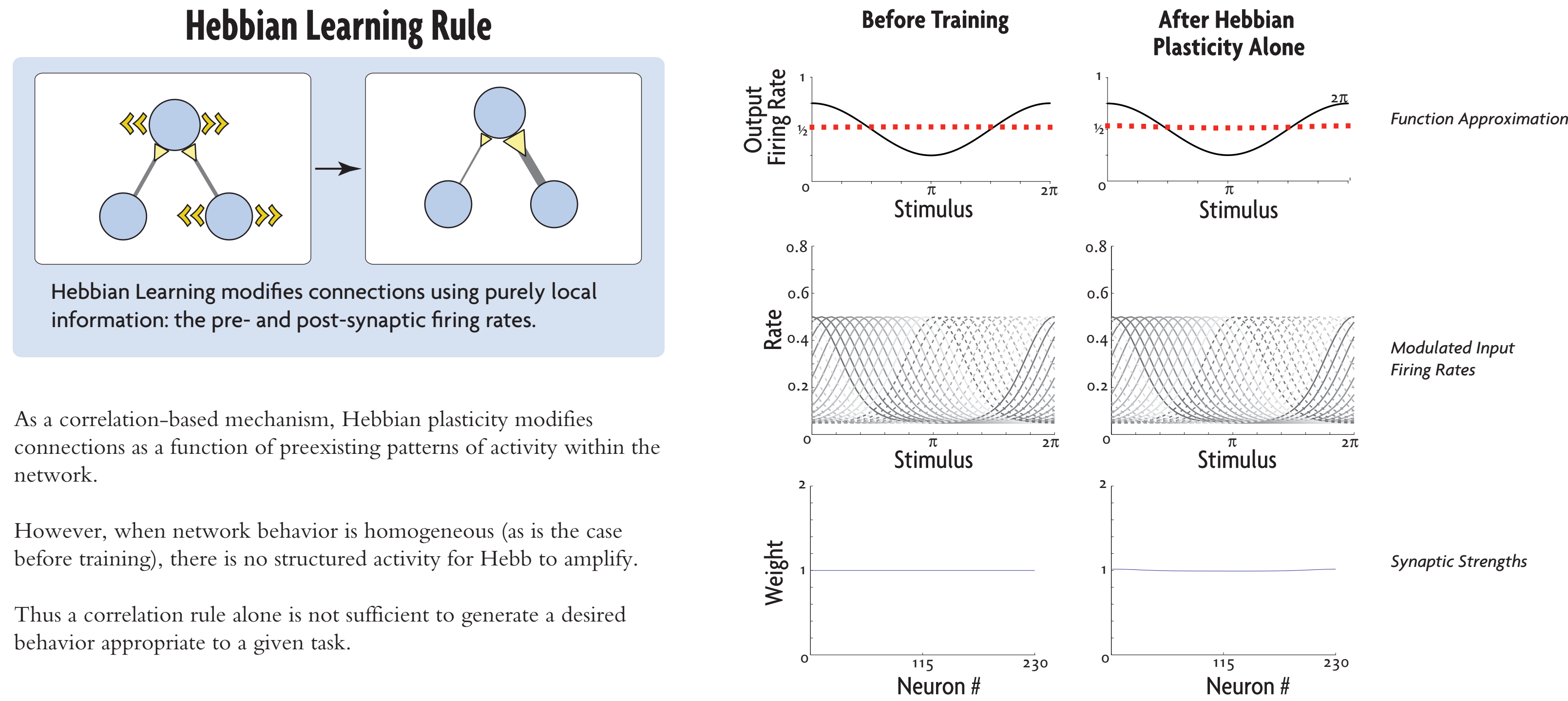


### Response Modulation-guided Learning

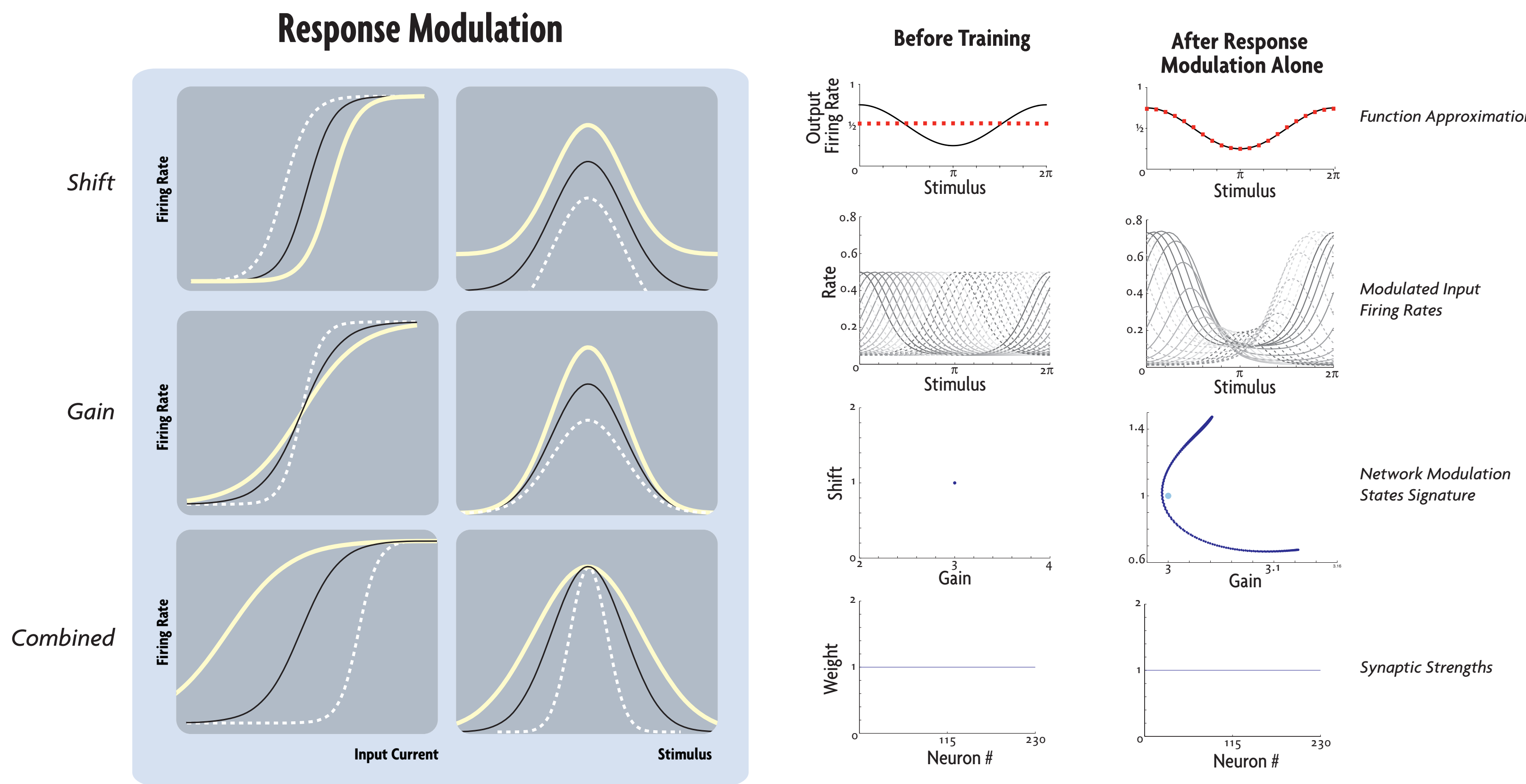


## The Chicken & Egg Problem of Plasticity

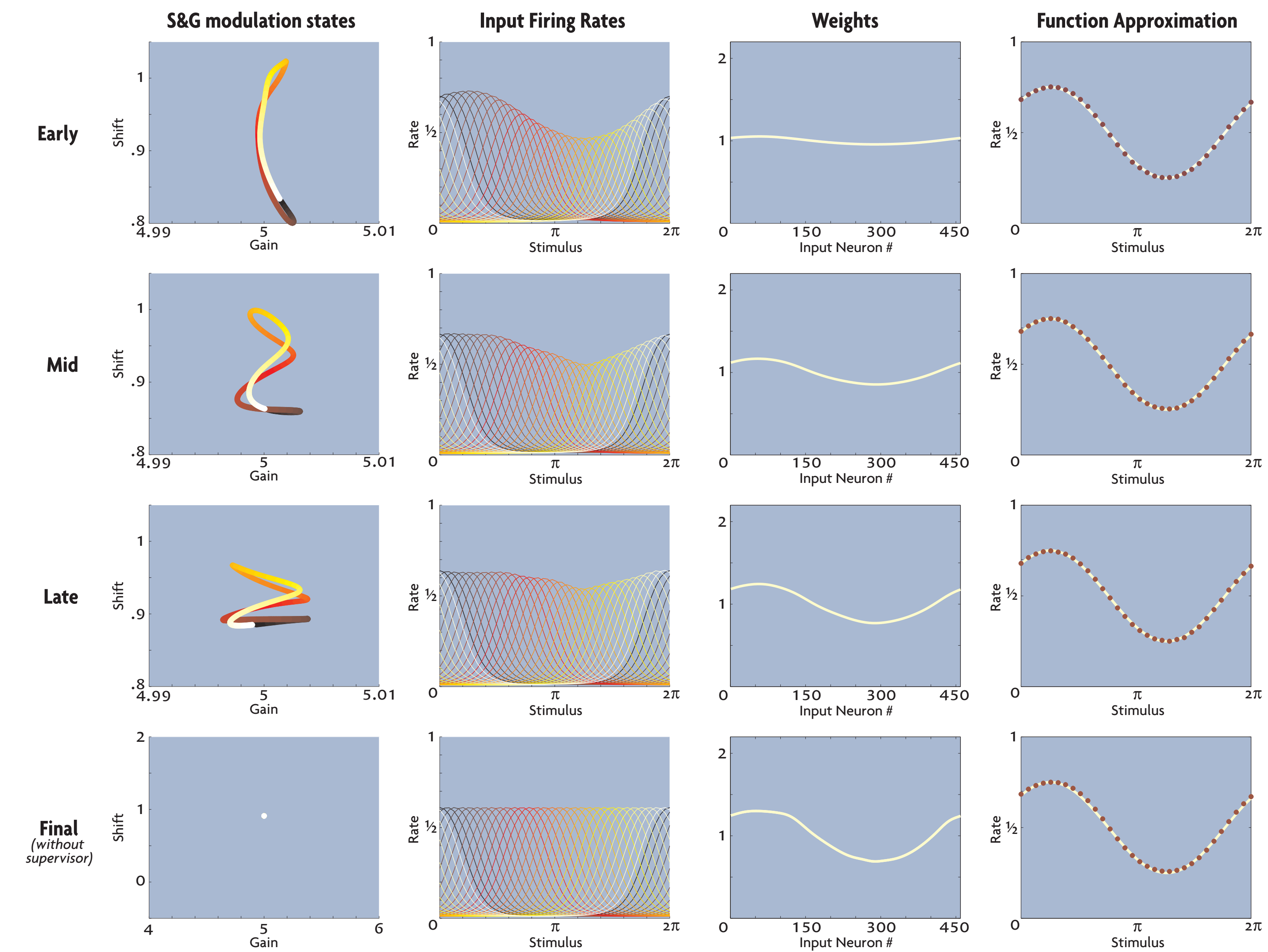
Hebbian plasticity can't create something from nothing...



...while Response Modulation can influence behavior, but cannot make permanent, synaptic changes to the network

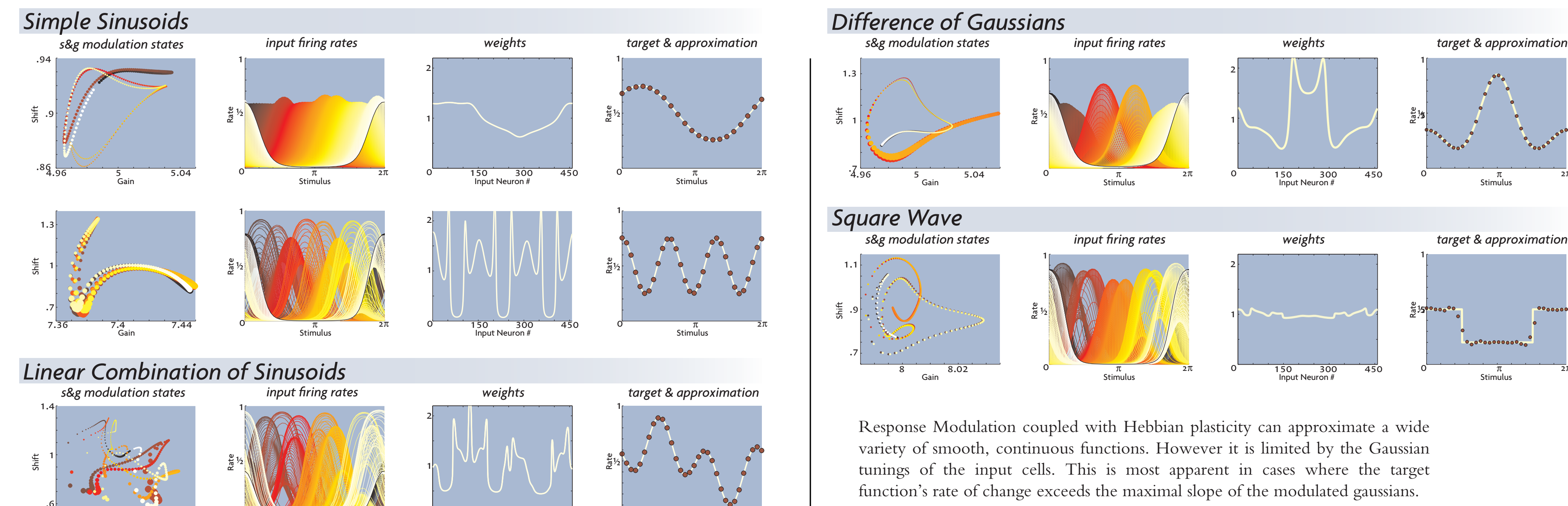


## Response Modulation-biased Hebbian Learning



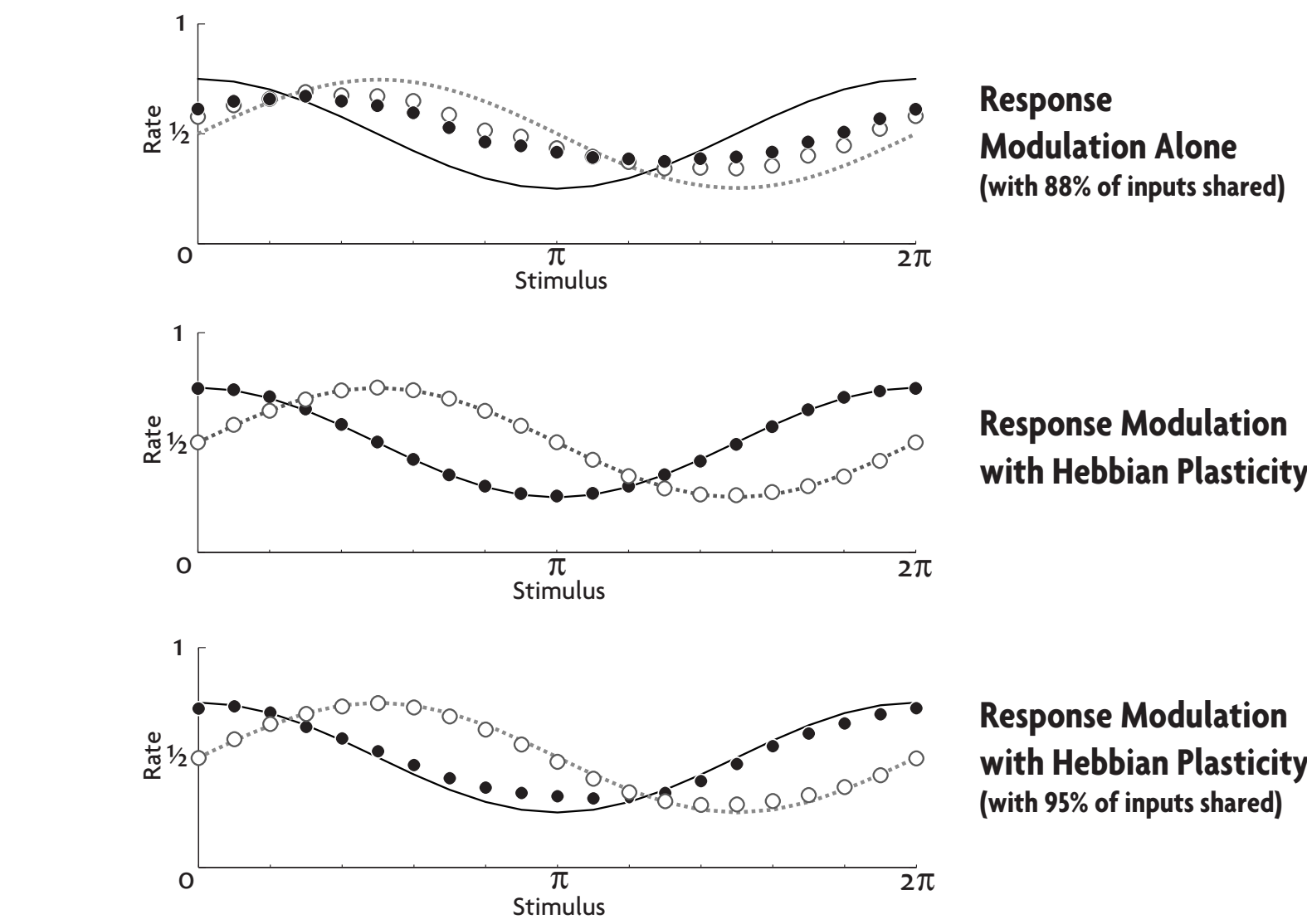
## Learning in Single Output Unit Networks

### Range & Limitations



## Multiple Outputs, Interference, and Bias

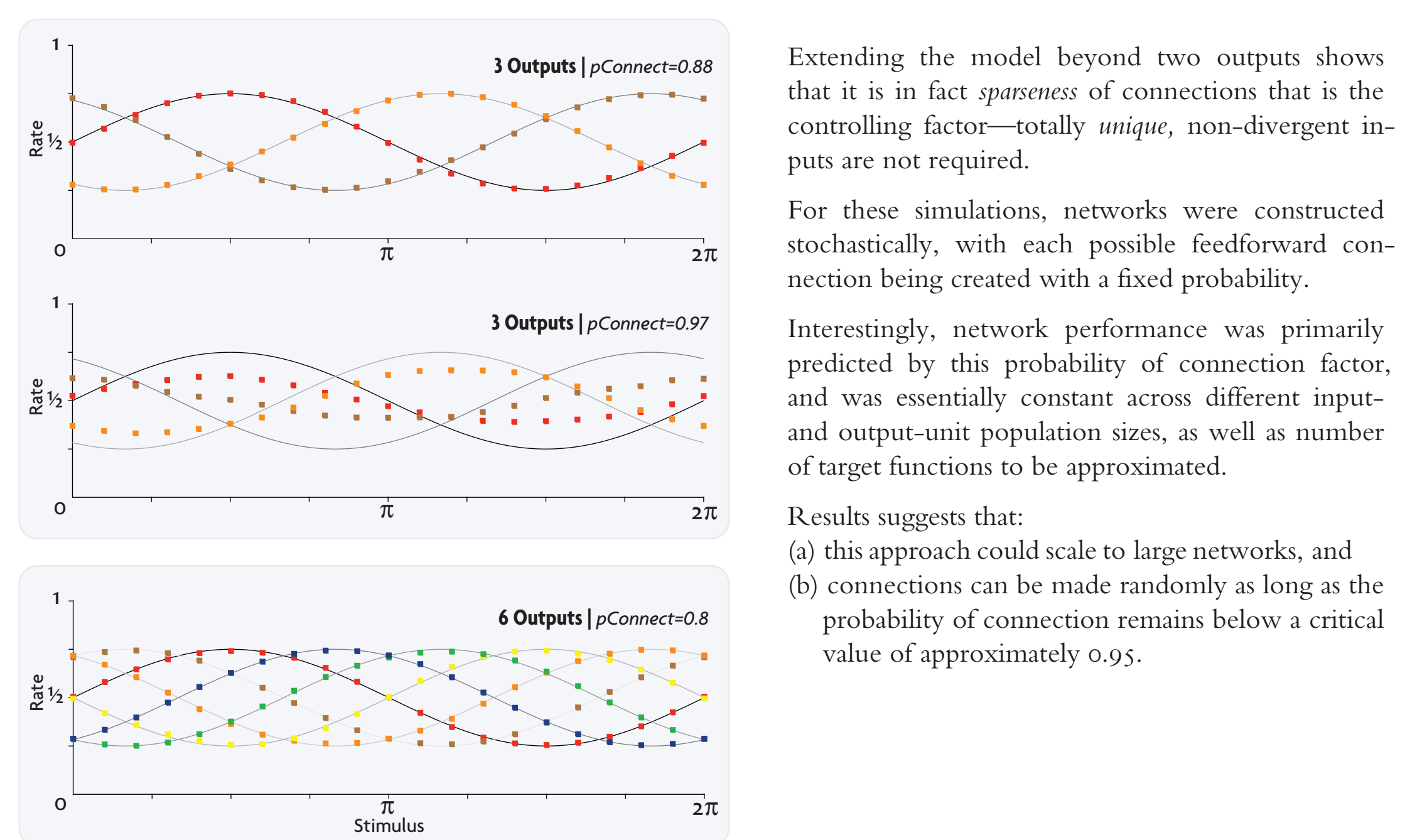
### Function Approximations with Two Output Units



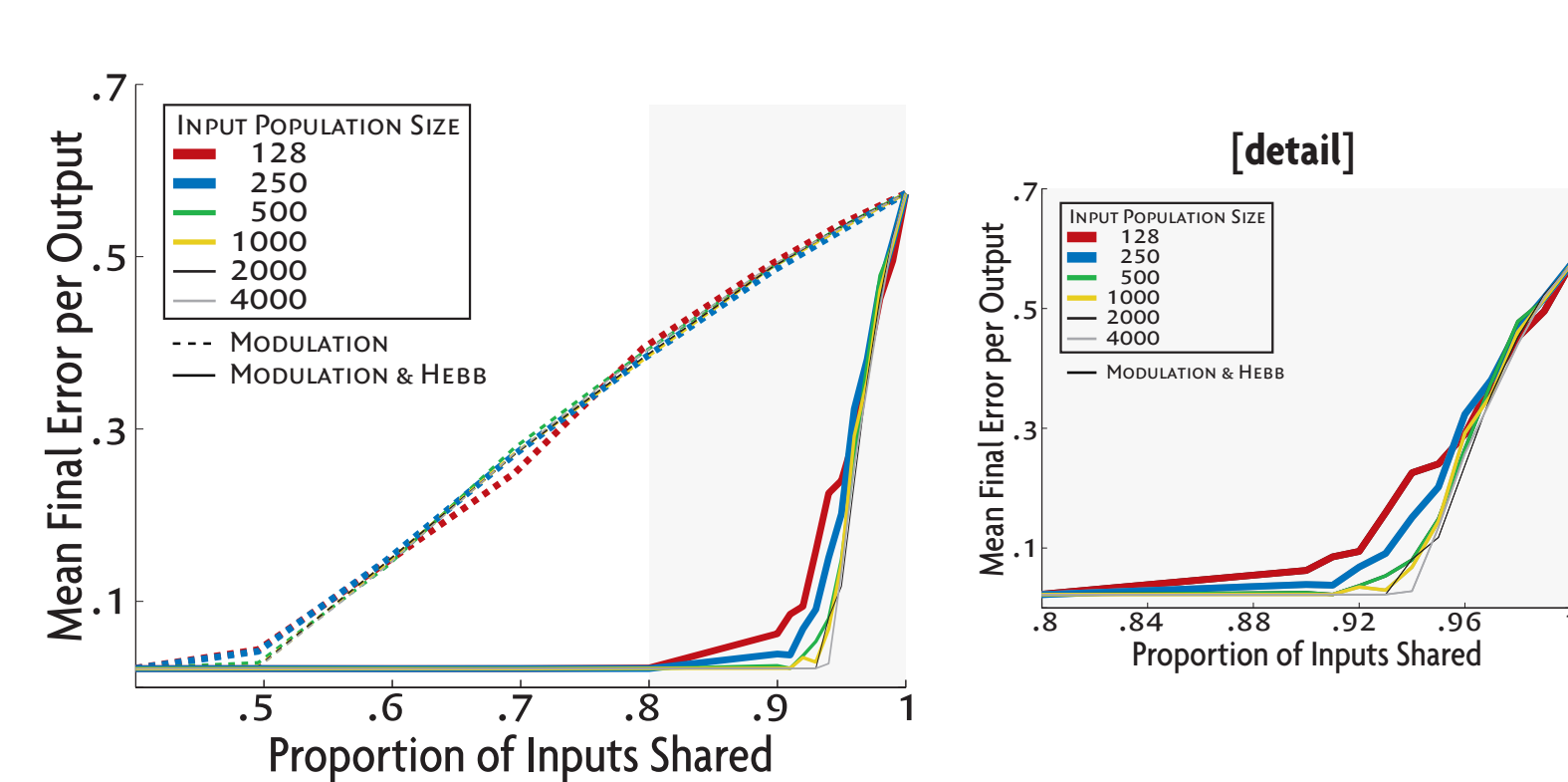
In networks with more than one output, each input cell may project to multiple target neurons—complicating the supervisor's task. In the two-unit case, there must be a sufficient number of uniquely connected input neurons to allow for different target functions to be approximated.

However, even in cases with too much overlap for the supervisor alone to impose a proper activity pattern, the relatively weak bias it provides can direct Hebbian plasticity to approximate the two target functions.

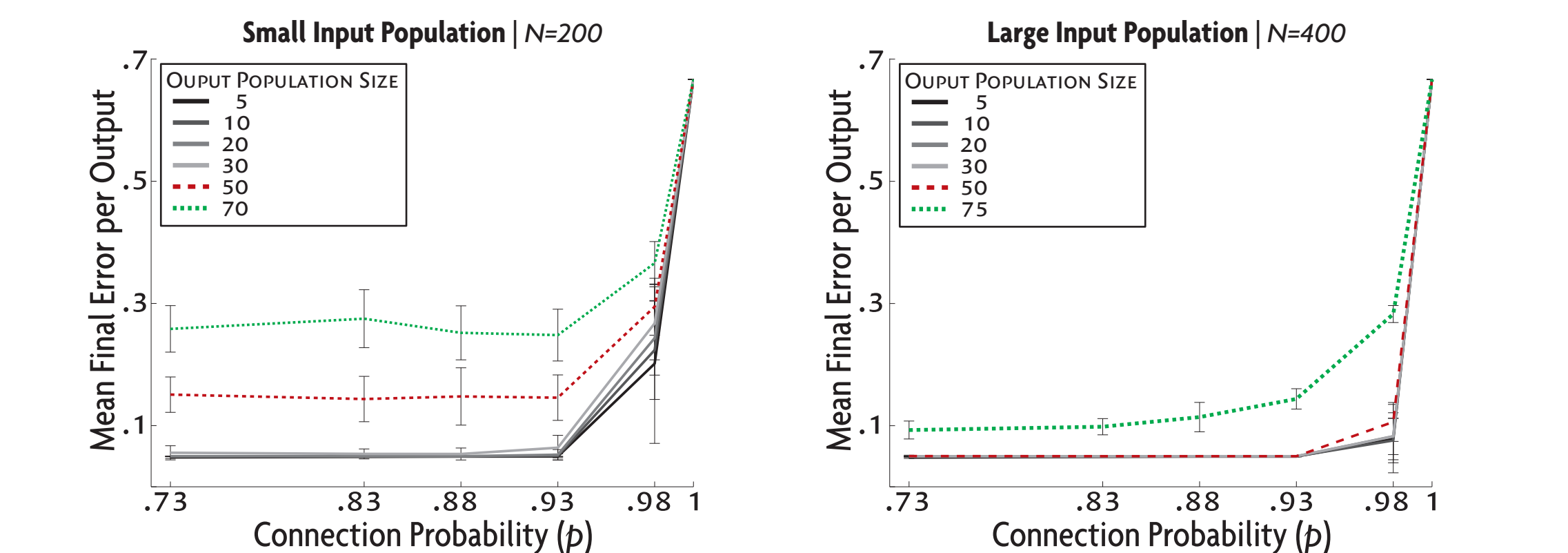
### Function Approximations with >2 Output Units



### Error vs. Number & Proportion of Unique Inputs

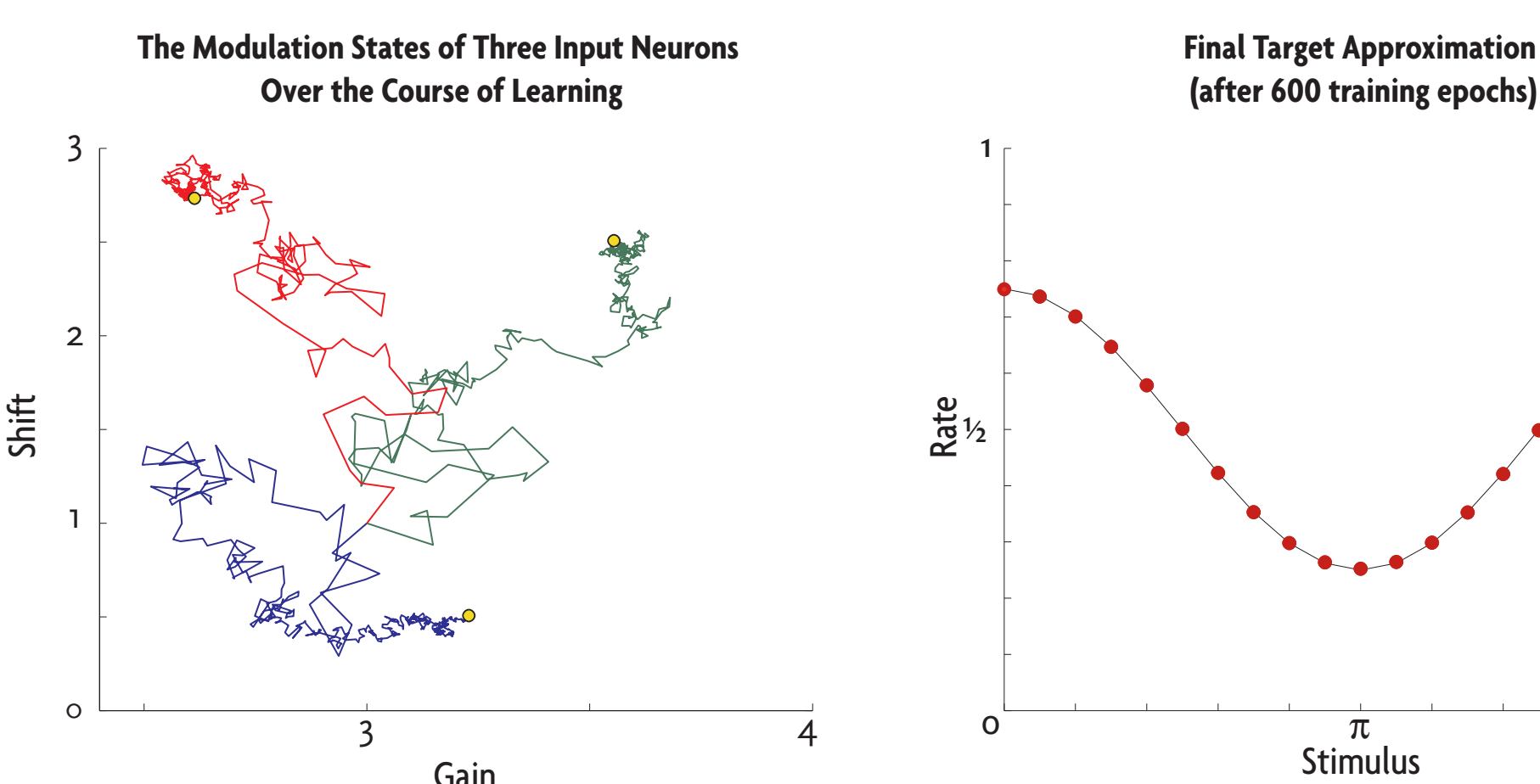


### Error vs. Number of Output Units



## Nature of the 'Supervisor'

### Random Walk/Reinforcement Learning Supervisor



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